

# Bloch Equations

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## 1 Introduction

For the rest of this note, we follow Bloch's notation and denote by  $\mathbf{M}$  the nuclear polarization, i.e, the net nuclear magnetic moment per unit volume.

## 2 Larmor precession

We assume the reader has basic familiarity with electromagnetism and classical mechanics. We start from the classical equation

$$\frac{d\mathbf{L}}{dt} = \boldsymbol{\tau}, \quad (1)$$

where  $\mathbf{L}$  denote the angular momentum of all the nuclei of interest and  $\boldsymbol{\tau}$  denote the net torque acting upon all the nuclei. Next, we recall another classical equation relating the aligning torque  $\boldsymbol{\tau}$  acting on a dipole from an externally applied magnetic field  $\mathbf{B}$ , which gives us

$$\boldsymbol{\tau} = \mathbf{M} \times \mathbf{B}. \quad (2)$$

Lastly, recall the gyromagnetic ratio  $\gamma$ , which gives us

$$\mathbf{M} = \gamma\mathbf{L}. \quad (3)$$

Hence, from (1), (2), and (3), we have

$$\frac{d\mathbf{M}}{dt} = \gamma\mathbf{M} \times \mathbf{B}. \quad (4)$$

### 3 Relaxation

The equation in (4) describe the Larmor precession of  $\mathbf{M}$  in an external magnetic field  $\mathbf{B}$ . However, Bloch noticed that the NMR nuclear induction signal decayed quickly. This motivated Bloch to propose the concept of relaxation, which describes how  $\mathbf{M}$  returns to its initial alignment parallel to  $\mathbf{B}$  with some equilibrium magnitude  $M_0$ .

Relaxation is characterized by two constants, i.e.,  $T_1$ , the longitudinal relaxation time, and  $T_2$ , the transversal relaxation time. Bloch assumed that both  $T_1$  and  $T_2$  relaxations follow first-order kinetics, i.e.,

$$\frac{dM_z}{dt} = -\frac{M_z - M_0}{T_1}, \quad (5)$$

$$\frac{dM_x}{dt} = -\frac{M_x}{T_2}, \quad (6)$$

$$\frac{dM_y}{dt} = -\frac{M_y}{T_2}. \quad (7)$$

### 4 Bloch Equations

Since (4) describes the rate of change in  $\mathbf{M}$  solely due to Larmor precession and (5), (6), and (7) describe the rate of change in  $\mathbf{M}$  solely due to relaxation, we can add (4), (5), (6), and (7), and have

$$\frac{dM_z}{dt} = \gamma(M_x B_y - M_y B_x) - \frac{M_z - M_0}{T_1}, \quad (8)$$

$$\frac{dM_x}{dt} = \gamma(M_y B_z - M_z B_y) - \frac{M_x}{T_2}, \quad (9)$$

$$\frac{dM_y}{dt} = \gamma(M_z B_x - M_x B_z) - \frac{M_y}{T_2}. \quad (10)$$

### 5 Solutions

For the sake of simplicity, consider the case of a constant external magnetic field

$$\mathbf{B} = \begin{pmatrix} 0 \\ 0 \\ B_0 \end{pmatrix}. \quad (11)$$

Notice that under the assumption in (11), (8) can be written as

$$\frac{dM_z}{dt} = -\frac{M_z - M_0}{T_1}, \quad (12)$$

whose solution is given by

$$M_z(t) = M_z(0)e^{-t/T_1} + M_0(1 - e^{-t/T_1}). \quad (13)$$

Notice that as  $t \rightarrow 0$ , we have  $M_z(t) \rightarrow M_0$ .

To simplify (9) and (10), use assumption (11) and recall Larmor equation

$$\omega_0 = \gamma B_0, \quad (14)$$

and we have

$$\frac{dM_x}{dt} = \gamma M_y B_z - \frac{M_x}{T_2} = \omega_0 M_y - \frac{M_x}{T_2}, \quad (15)$$

$$\frac{dM_y}{dt} = -\gamma M_x B_z - \frac{M_y}{T_2} = -\omega_0 M_x - \frac{M_y}{T_2}, \quad (16)$$

whose solution is given by

$$M_x(t) = e^{-t/T_2}(M_x(0) \cos \omega t + M_y(0) \sin \omega t), \quad (17)$$

$$M_y(t) = e^{-t/T_2}(M_y(0) \cos \omega t - M_x(0) \sin \omega t). \quad (18)$$